Emergent Gestural Scores in a Recurrent Neural Network Model of Vowel Harmony

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Modeling Phonology and Phonetics with a Recurrent Neural Network



phonological surface forms from underlying forms (Hare 1990; Prickett 2019)

Recurrent neural networks compute articulatory trajectories from strings of segments (Jordan 1986; Biasutto-Lervat & Ouni 2018)



Modeling the Phonology-Phonetics Interface with a Recurrent Neural Network

- Can a recurrent neural network learn to compute articulatory trajectories directly from input phonological segments without being provided any intermediate linguistic structure?
- If so, when tasked with learning a pattern of phonological alternation (e.g. vowel harmony), how does the network represent and generate the pattern?

GestNet: encoder-decoder network that generates articulatory trajectories from string of phonological input segments



Nzebi Stepwise Height Harmony

(Guthrie 1968, Clements 1991, Parkinson 1996, Kirchner 1996, Smith 2020)

In presence of trigger /-i/, each nonhigh vowel raises one 'step' along a height scale

		Non-Raising Context	Raising Context	Gloss
	u 🅤	[b <u>e</u> tə]	[b <u>i</u> t-i]	'carry'
e	0 5	[β <u>o</u> ːmə]	[β <u>u</u> m-i]	'breathe'
3	о —	[s <u>ɛ</u> bə]	[s <u>e</u> b-i]	'laugh'
a		[m <u>ɔ</u> nə]	[m <u>o</u> n-i]	'see'
		[s <u>a</u> lə]	[s <u>ɛ</u> l-i]	'work'

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of the Gestural Harmony Model

Representing Harmony with Gestures

- Articulatory Phonology (Browman & Goldstein 1986, 1989):
 - Dynamically-defined, goal-based units of phonological representation
 - Specified for target articulatory state (e.g. labial closure)
- Gestural Harmony Model (Smith 2016, 2018): harmony-triggering gesture extends to overlap gestures of other segments in a word (undergoers)



A Gestural Analysis of Nzebi (Smith 2020)

Vowel raising harmony due to overlap by upper surface narrowing gesture of suffix high vowel /i/



Modeling the Phonology-Phonetics Interface with a Recurrent Neural Network





Modeling the Phonology-Phonetics Interface in Gestural Phonology





GestNet



GestNet's Encoder-Decoder Architecture (Cho et al. 2014; Sutskever et al. 2014; Bahdanau et al. 2015; Luong et al. 2015)



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Encoder: process one input vector at each time step Decoder: produce one output vector at each time step

Training the Model

Segment	Constriction Degree Target	
i, u	Tongue Body 4	
е, о	Tongue Body 8	
ε, ο	Tongue Body 12	
а	Tongue Body 16	
b	Lip -2	
g	Tongue Body -2	

- Training data: 112 total (V)CV sequences
 - Inputs: symbols strings with C = {b, g} and
 V = {i, e, ε, a, o, u}
 - Outputs: artificially generated trajectories for lip and tongue body positions across ten timepoints
- Height harmony pattern: In VCV in which V₂ is high vowel /i/ or /u/, V₁ undergoes one-step raising (i.e. /eb-a/→[eba] but /eb-i/→[ibi])
- Trained twenty models for 200 epochs each



Results & Analysis



Model Accuracy



- All models produced highly accurate lip and tongue body trajectories for VCV sequences after training
- V₁ produced without raising before non-high vowels
- V₁ produced with one-step raising before high vowels



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What are our models learning when they learn to produce these patterns?

Examining Encoder-Decoder Attention



 Encoder-decoder attention provides simple recurrent neural networks with short memories a way to look back to encoder hidden states

 Degree of attention paid to an encoder hidden state can be used as measure of how much influence an input segment has on output at specific timepoint



Examining Encoder-Decoder Attention



Proposal: Patterns of encoder-decoder attention reflect patterns of gestural activation in a word's gestural score

- Effective attention: attention weight multiplied by magnitude of its encoder hidden state vector
- At each decoder timepoint, record vector of effective attention weights to determine degree to which how much or how little each encoder hidden state affects the decoder hidden state





Lighter color = more attention

- Attention maps show how much the model's decoder attends to each input segment at each time point
- Non-triggering V₂: V₁ and V₂ each receive attention during their own productions, but not while the other is being produced
- Consistent with sequential gestural activation





Lighter color = more attention

- Attention maps show how much the model's decoder attends to each input segment at each time point
- Triggering V₂:
 - V₁ receives attention during first half of word
 - V₂ receives attention throughout the entire word
- Consistent with overlapping gestural activation



Attention on V₁ at Each Medial Timepoint





- Mixed effects model confirms these attention patterns are significant
- During production of first syllable (decoder timepoints 2-5), V₁ input segment receives significantly more attention than during production of second syllable (decoder timepoints 6-9) (p < 0.001)
- Gesture of V₁ is active during first syllable and not active during second syllable

Attention on V₂ at Each Medial Timepoint





- Mixed effects model confirms these attention patterns are significant
- During production of first syllable (timepoints 2-5), harmonytriggering V₂ input segment receives significantly more attention than non-triggering V₂ (p < 0.001)
- Gesture of harmony-triggering V₂ is active during first syllable; gesture of non-triggering V₂ is not

Conclusion



Conclusion

- GestNet models reliably learn a pattern of stepwise height harmony
- Models develop emergent structure analogous to the abstract representations of gestural phonology
- Patterns of encoder-decoder attention are consistent with patterns of gestural activation assumed in the Gestural Harmony Model
- Next steps: additional model analysis, additional phonological patterns

